

## Anexa 4

### FISA DE VERIFICARE A INDEPLINIRII STANDARDELOR MINIMALE

Candidat Donca Radu-Călin, înscris la concursul pentru ocuparea postului de **Sef de Lucrări, perioada determinată**, la Facultatea Mecanică, Departament Mecatronica și Dinamica Mașinilor, poziția 16.

<b>Criteriu / subcriteriu</b>	<b>Evaluare</b>	<b>Document doveditor</b>
<b>1. Activitatea didactică</b>		
1.a. autor / coautor / lucrări didactice publicate la edituri recunoscute	0	(se regasesc in lista de lucrari)
1.b. autor / coautor / lucrări de laborator redactate și realizate practic	3	(se regasesc in lista de lucrari)
<b>2. Activitatea științifică</b>		
2. a. autor / coautor / lucrări științifice publicate (conform criteriilor minimale aprobate de Senat)	25	(se regasesc in lista de lucrari)
2. b autor / coautor / alte lucrări ( proiecte, studii, etc.)	3	(se regasesc in lista de lucrari)
2. c. participări în colective de cercetare	9	(se regasesc in lista contractelor de cercetare)
<b>3. Activitate în folosul comunității academice</b>		
3. a. activitate în comisii permanente la nivel de departament / facultate / universitate	Da – Cerc studențesc	Atestat departament / facultate/universitate
3. b. membru în structuri ale unor organizații naționale și internaționale	Da - AROTMM	Atasati copii dupa documente doveditoare

Data 9.01.2018

Semnătura 

#### **Instrucțiuni:**

- Candidatul completează coloana a II-a (evaluare), unde este cazul.
- Candidatul va atasa, dacă este cazul, documente doveditoare, în xerocopie, pentru acele criterii a căror evaluare nu este posibilă pe baza conținutului dosarului.



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## AVIZ

Comisia de analiză a dosarelor de concurs pentru posturile didactice, numită prin decizia Consiliului Facultății de Mecanică nr. 7/02.11.2017, întrunită în data de 11.01.2018, în urma analizării dosarului candidatului **Donca Radu Călin** pentru postul de **șef de lucrări** pe perioadă determinată, **poziția 16** din Statul de funcții al Departamentului de Mecatronică și Dinamica Mașinilor a constatat

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Design and control of a novel type of actuator for the Isoglide T3R1 Parallel Robot RC Donca, DC Popa, R Balan, V Iancu, M Manic Resilient Control Systems (ISRCS), 2010 3rd International Symposium on, 91-94	1	2010
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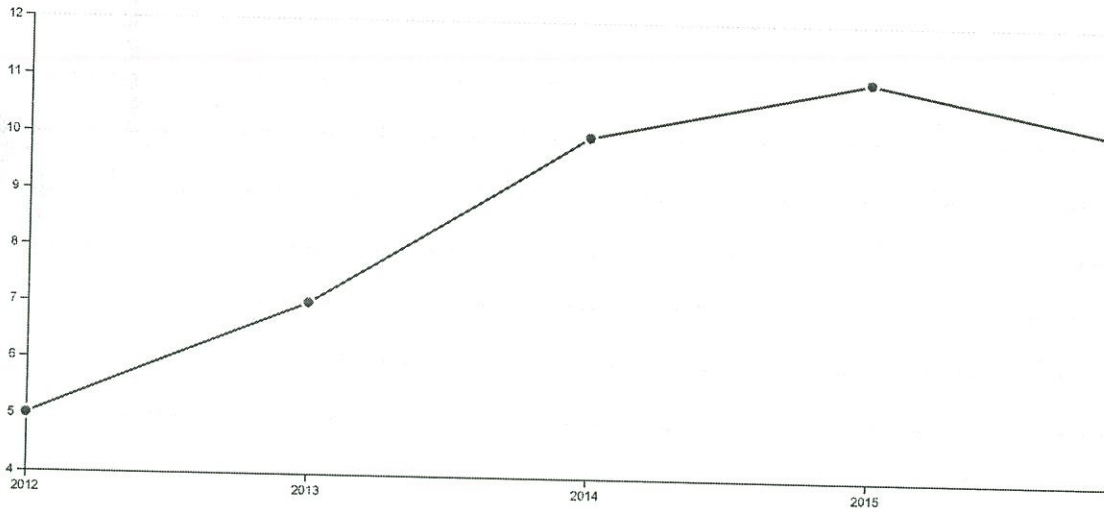
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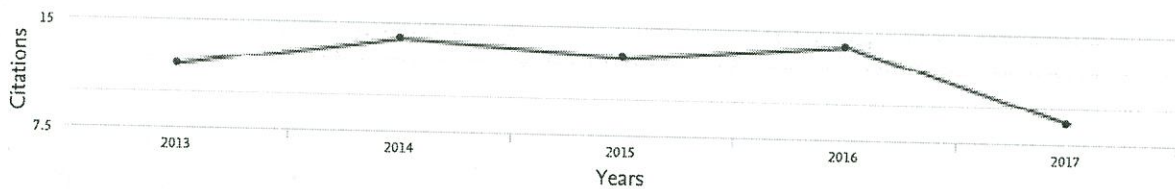
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