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1. **V. Miclea** and S. Nedevschi, "Real-Time Semantic Segmentation-Based Stereo Reconstruction," in *IEEE Transactions on Intelligent Transportation Systems*. doi: 10.1109/TITS.2019.2913883
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12. **V. C. Miclea**. Speeding-up polynomial multiplication on Virtex FPGAs: Finding the best addition method. In 2014 IEEE International Conference on Automation, Quality and Testing, Robotics, pages 1–5, May 2014.
13. **Vlad Miclea**. ProCoJuRi - A Processor Computing Just Right. Master Thesis, 2014.
14. **Vlad Miclea**. Cryptography on Reconfigurable Hardaware – Polynomial Multiplication and the Function Field Sieve Algorithm. License Thesis, 2013.
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Lista contracte de cercetare:

1) "PN III PCCF SEPCA (Semantic Visual Perception and Integrated Control for Autonomous Systems)", Project 9/2018 (2019-2022)
2) "Autonomous parking and driving UP-DRIVE, Horizon 2020 project, Grant 688652 (2016-2019).
3) "Reconfigurable ROS-based Resilient Reasoning Robotic Cooperating Systems - R5-COP", FP7 ARTEMIS project, (2014-2017)
4) "Cooperative Advanced Driving Assistance System Based on Smart Mobile Platforms and Road Side Units – SmartCoDrive", grant funded by Romanian Ministry of Education and Research, code PN II PCCA 2011 3.2-0742 din 03.07.2012 (2012-2016).

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