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PERSONAL INFORMATION

Rusu Călin



JOB APPLIED FOR

Technical University of Cluj-Napoca, Department of Mechatronics and Machine Dynamics – Associate Professor poz.11

WORK EXPERIENCE

2004-present Lecturer

Technical University of Cluj Napoca, Faculty of Automotive, Mechatronics and Mechanics, Departament of Mechatronics and Machine Dynamics, B-dul Muncii, nr. 103 -105, 400641, Cluj – Napoca, Romania

Didactic and research activities in the field of: Mechanisms, Measurement systems, Technical Optics, CAD. Institytional activities

2001-2004 University assistant

Technical University of Cluj Napoca, Faculty of Mechanics, Departament of Mechanisms, B-dul Muncii, nr. 103 -105, 400641, Cluj – Napoca, Romania

Didactic and research activities in the field of: Mechanisms, Measurement systems, Metrology, CAD

1998-2001 Preparator

Technical University of Cluj Napoca, Faculty of Mechanics, Departament of Mechanisms, B-dul

Muncii, nr. 103 -105, 400641, Cluj - Napoca, Romania

Didactic activities in the field of: Mechanisms.

EDUCATION AND TRAINING

1999-2005 PhD in Mechanical Engineering

Technical University of Cluj Napoca

Title: Contributions regarding the mechanisms for mechatronics

Scientific advisor: Prof. dr.ing. Vistrian Mătieș

1997-1998 Master - Advanced Methods and Tools in Engineering and Management

Quality Assurance

Technical University of Cluj Napoca. Faculty of Mechanics

1992-1997 Mechanical Engineer, specialization Precision Mechanics

Technical University of Cluj Napoca. Faculty of Mechanics

1988-1992 High school diploma

Industrial high School Mihai Viteazu, Turda

SPECIALIZATIONS

June 2009 Mechanical design with CATIA v5, Level III

Global Interface, Zaragoza, Spain

July, october 2008 Mechanical design with CATIA v5, Level I&II

Global Interface, Zaragoza, Spain

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December 2007

Advanced Simulink for System and Algorithm Modelling (Certificate of competency MathWorks)

MathWorks, Zurich, Switzerland

1 - 24.02.2002

Documentation internship

Instituto Universitario de Investigación de Ingeniería en Aragón si

Escuela Politécnica Superior, Zaragoza, Spain

21.07 - 19.08.2000

Documentation internship

Escuela Politécnica Superior, Zaragoza, Spain

RESEARCH ACTIVITIES

Research projects

Member of 18 research and institutional project teams

Publications

- 5 books (2 single author)
- 3 book chapters in national and international publishing houses (co-author)
- first author or co-author of more than 50 scientific papers published in journals or volumes of national or international conferences (18 indexed Web of Science of which 2 with impact factor)
- H-index: Web of Science: 3; Scopus: 4; Google Scholar: 6

Patents

RO123627-B1- Portable laboratory for mechatronic education, authors: Maties, V., Bălan, R., Rusu, C., Hancu, O., Lapusan, C., Besoiu, S.

Visiting professor

October 2015 - Design of Multifunctional Robotic Arms with Applications for In-Pipe Inspection Robots, Hochschule Esslingen, University of Applied Sciences, Faculty of Mechanical Engineering.

March 2019 - Introduction in Technical Optics, Kyrgyz State University of Construction, Transport and Architecture.

Reviews

Reviewer at MDPI journals: Applied Sciences, Machines, Actuators, Energies, Sensors and Robotics

PERSONAL SKILLS

Mother tongue

Romanian

Other language

UNDERSTANDING		SPEAKING		WRITING
Listening	Reading	Spoken interaction	Spoken production	
B2	B2	B2	B2	B2

English

Levels: A1/2: Basic user - B1/2: Independent user - C1/2 Proficient user Common European Framework of Reference for Languages

Communication skills

Good communication skills gained through:

- participation in teaching and research teams
- participation as a member in doctoral student guidance committees
- participating in national and international projects as well as attending conferences and workshops

Computer skills

- CATIAv5, Autodesk Inventor, SolidWorks, NX, Creo
- LabView, Matlab/Simulink
- programming skills in C#, Pascal
- Microsoft Office™

Driving licence

В

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ADDITIONAL INFORMATION

Publications (selection)

 Rusu, C., Tatar, M.O - Adapting Mechanisms for In-pipe Inspection Robots: A review, Applied Sciences, 12, 2022, ISSN 2076-3417 (IF 2.838)

- S. Noveanu, I.A Ivan, D.C. Noveanu, C. Rusu, D. Lates SiMFlex Micromanipulation Cell with Modular Structure, Applied Sciences 10, 2020, ISSN 2076-3417 (IF 2.637)
- C. Rusu, S Besoiu, MO Tatar Design and closed-loop control of a piezoelectric actuator, IOP Conference Series: Materials Science and Engineering, vol 1018, 2021, doi.org/10.1088/1757-899X/1018/1/012002.
- Rusu, C., Besoiu, S. Analysis of the displacement amplification ratio for a piezoelectric driven compliant mechanism, Acta Technica Napocensis, Series: Applied Mathematics, Mechanics and Engineering, Vol 64, nr I, pag 87-92, 2021, ISSN 1221-5872
- S. Noveanu, C. Rusu, C. Rancea, D. Lateş Research Concerning the End-effectors for SiMFlex Microgripper, IOP Conference Series: Materials Science and Engineering, Vol 724, nr 1, 2020, doi:10.1088/1757-899X/724/1/012055
- S. Noveanu, D.Lates, L.Fusariu, C. Rusu A New Compliant Microgripper and Study for Flexure Hinges Shapes, Proceedings of the 13th International Conference INTER-ENG 2019 in Procedia Manufacturing, vol 46, 2019, ISSN 2351-9789
- C. Rusu, S, Besoiu, K Vidrean, C Lapusan New approaches in online evaluation of photovoltaic systems efficiency by implementing IoT monitoring solutions, Acta Technica Napocensis, Series: Applied Mathematics, Mechanics and Engineering, Vol 62 nr IV, pag12-18, 2019, ISSN 1221-5872
- C. Rusu, T.L. Tiuca, S. Noveanu, D. Mândru A KBE tool for solving the mechanisms kinematics, The 7th International Conference on Advanced Concepts on Mechanical Engineering ACME2016, IOP Conference Series: Materials Science and Engineering, Vol 147, pp 652-656, ISSN 1757-8981
- T.L. Tiuca, C. Rusu, S. Noveanu, D. Mândru General KBE model with inheritance and multi-CAD support, The 7th International Conference on Advanced Concepts on Mechanical Engineering ACME2016, IOP Conference Series: Materials Science and Engineering, Vol 147, pp 536-543, ISSN 1757-8981
- Lapusan C., Rusu C., Brai, L., Mandru, D Development of a multifunctional robotic arm for in-pipe robots, Proceeding of the 7th IEEE International Conference: Electronics, Computers and Artificial Intelligence (ECAI), 2015. ISSN: 2378-7147

Projects (selection)

- Proiect ERASMUS 2022-1-RO01-KA220-HED-000088365 International Cooperation Framework for Next Generation Engineering Students NextGEng, coordonator UTCN, Conf.dr.ing. Ciprian Lapusan (in derulare)
- Proiect GNaC ARUT, cod 168, Nr.3030/05.02.2019 Sistem de micromanipulare cu actuatori piezoelectrici şi flexibilitate funcţională – SiMFlex, director proiect Conf.dr.ing. Noveanu Simona, perioada 2019 – 2020, Results: 1 ISI scientific paper, 4 BDI
- 3. Proiect ERASMUS 575660-EPP-1-2016-1-FI-EPPKA2-KA Smart HEI-Business collaboration for skills and competitiveness HEIBus, coordonator UTCN, Conf.dr.ing. Ciprian Lapusan, perioada 2017-2019. Rezultate: 1 BDI scientific paper
- Proiect ERASMUS 561894-EPP-1-2015-1-DE-EPPKA2-CBHE-JP Advancing University Education in Biomedical Engineering and Health Management in Kyrgyzstan KyrMEDU, coordonator UTCN Conf.dr.ing. Simona Noveanu, perioada 2018-2019. Results: lecture given at Kyrgyz State University
- Proiect ERASMUS 540425-LLP-1-2013-1-FI-ERASMUS-EKA Reshaped Partnerships for Competitiveness and Innovation Potential in Mechanical Engineering RePCI, Responsabil UTCN: Prof.dr.ing. Dan M\u00e4ndru, membru colectiv, perioada: perioada: 2014-2015.: Results: 2 BDI scientific paper, lecture given at Hochschule Esslingen
- Proiect POSDRU/87/1.3/S/64069 FlexFORM Program de formare profesionala flexibilă pe platforme mecatronice, Manager proiect: Prof.dr.ing. Matieş Vistrian, expert formare, perioada 2010-2013
- Proiect Capacități nr.111 / CP / I 14.09.2007 Laborator regional multifunctional de mecatronică, director de contract: Prof. dr. ing. Mătieş Vistrian, perioada: 2007–2010, Results: 1 patent
- Proiect Parteneriate Nr 21-003/2007 Creşterea eficienţei conversiei energiei solare în platforme fotovoltaice orientabile, PLATSOL-PV, Responsabil ştiinţific Partener UTCN: Prof. dr. ing. Mătieş Vistrian, perioada: 2007–2010.
- Proiect IDEI ID_1056, Contract nr. 85/01.10.2007 Modelarea, simularea şi realizarea unor familii de sisteme robotizate pentru inspecţie şi explorare, director de contract: Prof. dr. ing. Olimpiu Tatar, perioada: 2007–2010.
- Grant A/2005 CNCSIS Cercetări privind sinteza axelor cinematice în mecatronică, director de proiect: Prof.dr.ing. Mătieş Vistrian, perioada 2004-2006.

Memberships

- Romanian Association for the Theory of Machines and Mechanisms ARoTMM
- Romanian Society of Robotics

Cluj Napoca 6.06.2023

