

PERSONAL INFORMATION

Toucan Paul-George-Mihai

THE JOB AND THE POSITION
APPLIED FOR

Associate Professor 17, FIIRMP/ISM

PROFESSIONAL EXPERIENCE

24.02.2020 – present

Lecturer

Technical University of Cluj-Napoca, Faculty of Industrial Engineering, Robotics and Production Management, Mechanical Systems Engineering Department

Didactic activities in the field: computer programming and operation, robots with parallel structures, medical robotics

01.10. 2020 – present

Type or sector of activity Education and Research

Scientific researcher grade III

Technical University of Cluj-Napoca, Faculty of Industrial Engineering, Robotics and Production Management, Mechanical Systems Engineering Department

Scientific research activities in the following fields: robotics, mechatronics, simulation techniques, kinematics and dynamics of parallel robots, surgical robots, robots for cancer diagnosis and treatment, robots for medical rehabilitation.

01.10.2015-23.02.2020

Type or sector of activity Education and Research

Teaching Assistant

Technical University of Cluj-Napoca, Faculty of Industrial Engineering, Robotics and Production Management, Mechanical Systems Engineering Department

Didactic activities in the field: computer programming and operation, robots with parallel structures, medical robotics

01.10.2014-30.09.2020

Type or sector of activity Education and Research

Research Assistant

Technical University of Cluj-Napoca, Faculty of Industrial Engineering, Robotics and Production Management, Mechanical Systems Engineering Department

Scientific research activities in the following fields: robotics, mechatronics, simulation techniques, kinematics and dynamics of parallel robots, surgical robots, robots for cancer diagnosis and treatment, robots for medical rehabilitation.

17.08.2011-30.09.2014

Type or sector of activity Education and Research

Head of department

SC ARMATURA SA

Coordination of the processing department; Processing parts according to the production plan; Completion of parts according to the delivery plan; Preparation of the production plan within the department; Human resources management within the processing department;

Preparation of the work plan and auxiliary documents; Preparation and procurement of the necessary materials; Implementation and operation of SAP software; Coordinator of the maintenance team in the Processing and Assembly section; Drawing up repair and maintenance plans.

Type or sector of activity Industry

EDUCATION AND TRAINING

01.10.2014-26.11.2018

PhD degree

Write the EQF level,
if you know it

Technical University of Cluj-Napoca, Faculty of Industrial Engineering, Robotics and Production Management

The field of Mechanical Engineering,
PhD thesis title: Development of new parallel robots for prostate biopsy

01.10.2010-30.06.2012

Master's degree

Technical University of Cluj-Napoca, Faculty of Industrial Engineering, Robotics and Production Management, Robotics Specialization

01.10.2006-09.06.2010

Bachelor's degree

Technical University of Cluj-Napoca, Faculty of Industrial Engineering, Robotics and Production Management, Robotics Specialization

01.09.2002-30.06.2006

Baccalaureate diploma

Avram Iancu Theoretical High School, Cluj-Napoca, Mathematics-Informatics section

PERSONAL SKILLS

Language (s) default (s)

Write the mother tongue / mother tongues

Other known foreign languages

	UNDERSTANDING		SPEAKING		WRITING
	Listening	Reading	Participating in the conversation	Oral speech	
English	B2	B2	B2	B2	B2
French	A2	A2	A2	A2	A2

Levels: A1/2: Elementary user - B1/2: Independent user - C1/2: Experienced user
Common European Framework of Reference for Foreign Languages

Communication skills

Good communication skills obtained through didactic activity, participation in scientific conferences, writing scientific papers and management activity of the Mechanical Processing section

Organizational/managerial skills

Organizational and managerial skills obtained during the activity as head of section (coordination of over 50 employees)

Skills acquired in the workplace

Kinematic and dynamic modeling of robots, programming of robots and mechanical systems, CAD, design engineering.
Production planning, human resources organization, quality control, process optimization output

Computer skills

Operating systems: Windows, Android.
Programming: Matlab, C, C++, Pascal, Java, JavaScript, HTML, Code Blocks, Visual Studio, LabView.
CAD/CAM: Siemens NX, AutoCAD, Catia, Delmia, 3DMaxStudio, SolidWorks, BricsCAD.
Office tools: MS Office, Corel Draw, Visio

Driver's license

AM, B1, B

ADDITIONAL INFORMATION

Publications

Rus, G.; Andras, I.; Vaida, C.; Crisan, N.; German, B.; Radu, C.; Tucan, P.; Iakab, S.; Hajjar, NA; Pisla, D. Artificial Intelligence-Based Hazard Detection in Robotic-Assisted Single-Incision Oncologic Surgery. *Cancers* 2023, 15, 3387. <https://doi.org/10.3390/cancers15133387>

Covaciu, F.; Crisan, N.; Vaida, C.; Andras, I.; Pusca, A.; German, B.; Radu, C.; Tucan, P.; Al Hajjar, N.; Pisla, D. Integration of Virtual Reality in the Control System of an Innovative Medical Robot for Single-Incision Laparoscopic Surgery. *Sensors* 2023, 23, 5400. <https://doi.org/10.3390/s23125400>

Tohanean, N.; Tucan, P.; Vanta, O.-M.; Abrudan, C.; Pintea, S.; German, B.; Burz, A.; Banica, A.; Vaida, C.; Neguran, YES; et al. The Efficacy of the NeuroAssist Robotic System for Motor Rehabilitation of the Upper Limb—Promising Results from a Pilot Study. *J. Clin. Med.* 2023, 12, 425. <https://doi.org/10.3390/jcm12020425>

Tucan, P.; Vaida, C.; Horvath, D.; Caprariu, A.; Burz, A.; German, B.; Iakab, S.; Pisla, D. Design and Experimental Setup of a Robotic Medical Instrument for Brachytherapy in Non-Resectable Liver Tumors. *Cancers* 2022, 14, 5841. <https://doi.org/10.3390/cancers14235841>

Pisla, D.; Birlescu, I.; Crisan, N.; Pusca, A.; Andras, I.; Tucan, P.; Radu, C.; German, B.; Vaida, C. Singularity Analysis and Geometric Optimization of a 6-DOF Parallel Robot for SILS. *Machines* 2022, 10, 764. <https://doi.org/10.3390/machines10090764>

Tarnita, D.; Geonea, ID; Pisla, D.; Carbone, G.; German, B.; Tohanean, N.; Tucan, P.; Abrudan, C.; Tarnita, DN Analysis of Dynamic Behavior of ParReX Robot Used in Upper Limb Rehabilitation. *Appl. Sci.* 2022, 12, 7907. <https://doi.org/10.3390/app12157907>

Gherman B, Hajjar NA, Tucan P, Radu C, Vaida C, Mois E, Burz A, Pisla D. Risk Assessment-Oriented Design of a Needle Insertion Robotic System for Non-Resectable Liver Tumors. *Healthcare (Basel)*. 2022 Feb 18;10(2):389. doi: 10.3390/healthcare10020389. PMID: 35207006; PMCID: PMC8872014.

Geonea, ID; Tarnita, D.; Pisla, D.; Carbone, G.; Bolcu, A.; Tucan, P.; Georgescu, M.; Tarniță, DN Dynamic Analysis of a Spherical Parallel Robot Used for Brachial Monoparesis Rehabilitation. *Appl. Sci.* 2021, 11, 11849. <https://doi.org/10.3390/app112411849>

Birlescu, I.; Husty, M.; Vaida, C.; German, B.; Tucan, P.; Pisla, D. Joint-Space Characterization of a Medical Parallel Robot Based on a Dual Quaternion Representation of SE(3). *Mathematics* 2020, 8, 1086. <https://doi.org/10.3390/math8071086>

Tucan, P.; Vaida, C.; Plitea, N.; Pisla, A.; Carbone, G.; Pisla, D. Risk-Based Assessment Engineering of a Parallel Robot Used in Post-Stroke Upper Limb Rehabilitation. *Sustainability* 2019, 11, 2893. <https://doi.org/10.3390/su11102893>

PATENTS

N. Plitea, D. Pisla, C. Vaida, B. Gherman, P. Tucan, C. Govor, F. Covaciu: Family of innovative parallel robots for transperineal prostate biopsy, Patent pending: A/00191/ 13.03.2015.

C. Vaida, D. Pisla, P. Tucan, N. Plitea, B. Gherman: Parallel robot for transperineal prostate biopsy. Patent pending 00761/26.10.2015.

C. Vaida, I. Birlescu, B. Gherman, P. Tucan, N. Plitea, D. Pisla: "Automated medical instrument for robotic assisted prostate biopsy", Patent pending: A/00936/29.11.2016.

D. Pisla, C. Vaida, I. Birlescu, F. Graur, B. Gherman, P. Tucan, N. Plitea: "Automated medical instrument for radiofrequency ablation", patent pending: A00379/10.06.2017.

D. Pisla, C. Vaida, I. Birlescu, F. Graur, B. Gherman, P. Tucan, N. Plitea: "Automated medical instrument with multiple needles for brachytherapy", patent pending: A00431/12.09.2017.

Pisla, D., Birlescu, I., Vaida, C., Gherman, B., Tucan, P., Plitea, N. Parallel robot for lower limb rehabilitation, RO-133814/29.10.2021.

Parallel robot for mobility rehabilitation of the lower limb, Authors: Pislă Doina, Birlescu Iosif, Vaida Călin, Gherman Bogdan, Tucan Paul, Plitea Nicolae, patent pending A00334/04.06.2019.

Automated medical instrument for the manipulation of a laparoscopic ultrasound probe. Authors: Birlescu, I., Vaida, C., Gherman, B., Burz, A., Tucan, P., Plitea, N., Pisla, D. patent pending

PRoHep-LCT- Parallel robot for the minimally invasive treatment of hepatic carcinoma. Authors: Plitea, N., Pisla, D., Vaida, C., Gherman, B., Tucan, P. patent pending A1017/03.12.2018.

Parallel modular robotic system for the ultrasound intraoperative probe guidance and the manipulation of instruments for the treatment of hepatic tumors. Authors: Vaida, C., Pisla, D., Plitea, N., Gherman, B., Tucan, P. patent pending A01143/24.12.2018

Parallel robot for mobility rehabilitation of the lower limb, Pisla, D., Gherman, B., Nadas, I., Pop, N., Craciun, F., Tucan, P., Vaida, C., Carbone, G, Birlescu, I., Plitea, N., Patent number OSIM: RO133815/29.10.2021

Family of modular parallel robots with active translation joints for SILS", Authors: Pisla Doina, Birlescu Iosif, Vaida Calin, Tucan Paul, Gherman Bogdan, Plitea Nicolae, registration no. OSIM A00733/03.12.2021.

Family of modular robots for SILS with kinematic constraint at the insertion point", Authors: Vaida Calin, Pisla Doina, Birlescu Iosif, Gherman Bogdan, Tucan Paul, Plitea Nicolae, registration no. OSIM A00734/03.12.2021.

Parallel robotic system for bilateral medical recovery of the shoulder joint, Tucan, P., Pisla, D., Vaida, C., Pisla, A., Gherman, B., Birlescu, I., no. OSIM registration: A / 00683-12.11.2021

Member in research projects

ATHENA- New smart and adaptive robotics solutions for personalized minimally invasive surgery in cancer treatment, Project coordinated by the Technical University of Cluj-Napoca- CESTER, Project manager: Dr. Ing. Damien CHABLAT, Implementation period: July 2023 – June 2026

ASKLEPIOS- New frontiers in adaptive modular robotics for patient-centered medical rehabilitation, Project coordinated by the Technical University of Cluj-Napoca – CESTER, Project manager: Assistant Professor Ing. Jose MACHADO PhD, Implementation period: July 2023-June 2026.

Challenge - New frontiers in robotic assisted single port surgery: a novel robotic system with dexterous instruments. National Exploratory Project, financed by the Executive Agency for Higher Education, Research, Development and Innovation Funding (UEFISCDI) Project code: PN-III-P4-ID-PCE-2020-0572-PCE-171, Contract no: PCE 171 from 17 /02/2021, Project duration: 2021-2023. Project Coordinator: Prof. Dr. Eng. Doina PISLA

Enhance - Innovative safe robotic system for enhanced patient-centered treatment of liver cancers. National Experimental Demonstration Project, financed by the Executive Agency for Higher Education, Research, Development and Innovation Funding (UEFISCDI) Project code: PN-III-P2-2.1-PED2021-2790, Contract no: 694PED from 24/06/2022, Project duration: 2022-2024. Project Coordinator: Prof. Dr. Eng. Doina Pisla

Hope2Walk - An innovative modular rehabilitation robot for the efficient therapy of lower limb motor deficit. National Experimental Demonstration Project, financed by the Executive Agency for Higher Education, Research, Development and Innovation Funding (UEFISCDI) Project code: PN-III-P2-2.1-PED2021-3430, Contract no: 608PED from 24/06/2022, Project duration: 2022-2024. Project Coordinator: Prof. Dr. Ing. Calin Vaida

Wisdom of Age - A Seniors Digital Platform for Knowledge Transfer towards Industrial Companies. Project funded by AAL Programme, co-funded by the European Commission and National Funding Authorities of Romania, Switzerland and Belgium, Project code: aal-2020-7-83-CP. UTCN responsible: Prof. Dr. Eng. Doina PISLA

APOLLO - Intelligent tele-robotic systems for the personalized treatment of neuromotor deficit to increase the patients quality of life. Project funded through the Competitiveness Operational Program 2014-2020, with the support of the European Union, under the Call Innovative Technological Projects - 2022, no. 34007/13.01.2023, UTCN responsible: Prof. Dr. Eng. Doina PISLA.

NeuroAssist - An innovative modular robotic system for the rehabilitation of brachial monoparesis. National Experimental Demonstration Project, financed by the Executive Agency for Higher Education, Research, Development and Innovation Funding (UEFISCDI) Project code: PN-III-P2-2.1-PED2019-3022, Contract no: 546PED from 02/11/2020, Project duration: 2020-2022. Project Coordinator: Prof. Dr. Eng. Doina Pisla

OnTarget - Innovative robotic guided instruments for the treatment of malignant tumors. National Experimental Demonstration Project, financed by the Executive Agency for Higher Education, Research, Development and Innovation Funding (UEFISCDI) Project code: PN-III-P2-2.1-PED2019-4375, Contract no: 397PED from 02/11/2020, Project duration: 2020-2022. Project Coordinator: Prof. Dr. Ing. Calin VAIDA

SAFE - Robotic Assisted Protection Cabin for Collecting Biological Samples with Airborne Pathogens. National Technological Transfer Project, financed by the Executive Agency for Higher Education, Research, Development and Innovation Funding (UEFISCDI) Project code: PN-III-P2-2.1-PTE-2019-0160, Contract no: 65 PTE/2020 from 01/ 09/2020, Project duration: 2020-2022. Project Coordinator: Prof. Dr. Eng. Doina PISLA

IMPROVE - High accuracy innovative approach for the robotic assisted intraoperative treatment of hepatic tumors based on imaging-molecular diagnosis. National Complex Project for Research, Development and Innovation, financed by the Executive Agency for Higher Education, Research, Development and Innovation

Funding (UEFISCDI) Project code: PN-III-P1-1.2-PCCDI2017-0221, Contract no: 59/1 March 2018, Project duration: 2018-2020. Project Coordinator: Prof. Dr. Eng. Doina PISLA

AgeWell - Innovative Approaches Regarding Rehabilitation and Assistive Robotics for Healthy Aging. Competitiveness Operational Program 2014-2020, Priority Axis 1 – Research, Technological Development and Innovation (Rd&I) to Support Economic Competitiveness and Business Development. Co-financed through the European Fund for Regional Development Project code: ID P_37_215 MySMIS 2014 Code: 103415. Implementation period: September 2016-August 2020. Project coordinated by the Technical University of Cluj-Napoca (CESTER). Project manager: Prof. Dr. Ing. Carbone GIUSEPPE

Heal4Liv - Innovative robotic system for cancer treatment. Funded by the European Institute of Innovation and Technology (EIT-Health) through InnoStars. Implementation period: April 2020-December 2020. Project coordinated by the Technical University of Cluj-Napoca (CESTER). Project manager: PConf. Dr. Eng. Bogdan Gherman

InnoHealth - An innovative robotic system for upper limb rehabilitation. Funded by the European Institute of Innovation and Technology (EIT-Health) through InnoStars. Implementation period: August 2019-December 2019. Project coordinated by the Technical University of Cluj-Napoca (CESTER). Project manager: Prof. Dr. Eng. Doina PISLA

ROBOCORE - Robotic assisted prostate biopsy, a high precision innovative method. National project PCCA TYPE 2, financed by Executive Unit for High Education Financing, Research, Development and Innovations (UEFISCDI) Project code : PN-II-PT-PCCA-2013-4-0647, Contract number: 247/2014, Project duration: 2014-2016. Project manager: Prof. Dr. Eng. Doina PISLA

ACCURATE - A multi-purpose Needle Insertion device for the diagnosis and treatment of cancer. National project PCCA TYPE 2, financed by Executive Unit for High Education Financing, Research, Development and Innovations (UEFISCDI) Project code : PN-II-RU-TE- 2014-4-0992, Contract number: 59 /2015, Project duration: 2015-2017. Project manager: Assoc. Prof. Dr. Eng. Calin Vaida

SPINE - Diagnosis and therapy system for spine disorders. National project PCCA TYPE 2, financed by Executive Unit for High Education Financing, Research, Development and Innovations (UEFISCDI) Project code: PN-II-PT-PCCA-2013-4-1596, Contract number: 227/2014, Project duration: 2015-2017. Project coordinated by the "Transylvania" University of Brasov, Project manager: Assoc. Prof. Dr. Eng. Butnariu Silviu

Bilateral research project Romania-Austria: Developing methods to evaluate the accuracy of potential parallel robots for medical applications, Project no 745/2014 (2014-2015), Director Romania: Prof. Doina PISLA, Director Austria: Prof. Manfred Husty.

01/09/2024
Cluj-Napoca

Tucan Paul
